



**Fun Game For  
Basic Humanoid  
Control**

# vEXCODE VR

## Activities

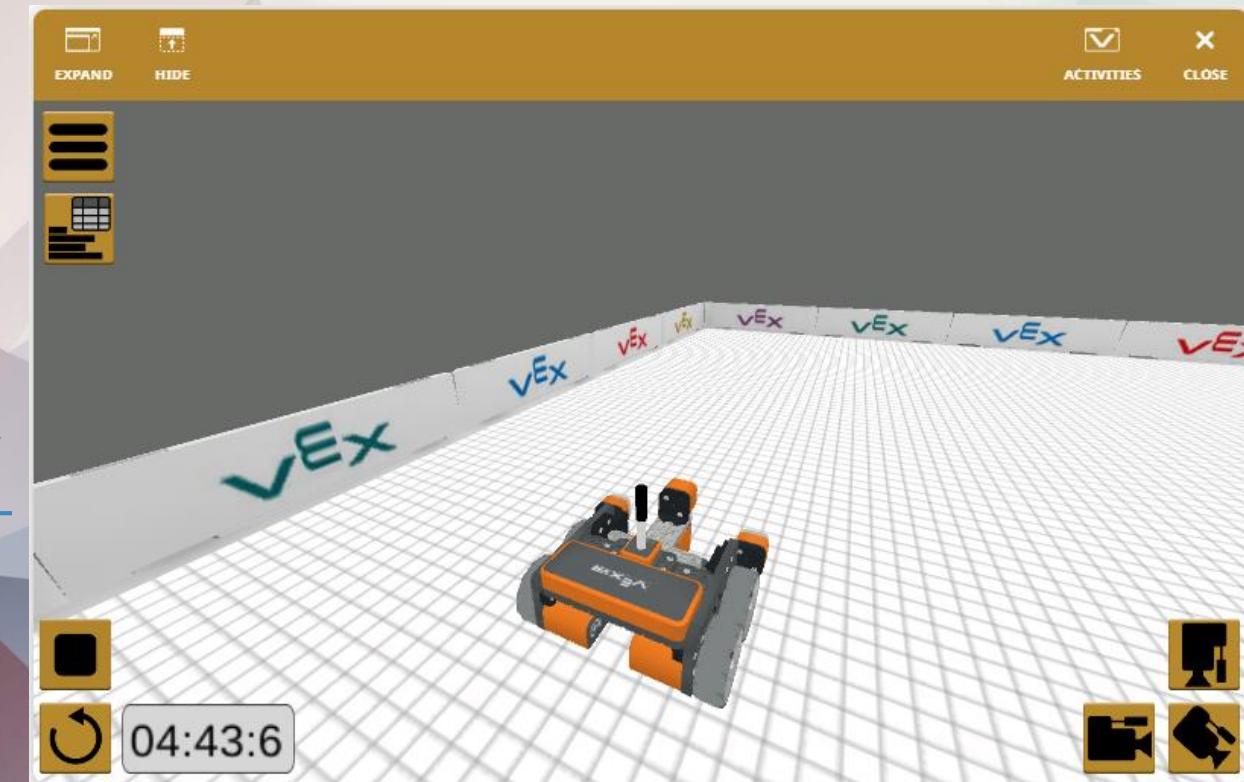


Welcome to VEXcode VR! It's a great platform for learning programming and robotics. Here are some tips to help you get started:

**With Vexcode Vr, you can create simple programs.** Begin by writing simple programs to move the robot forward or turn. Experiment with different commands to see how the robot responds.

# try this move..

- Open web  
<https://vr.vex.com/>



# VEXcode VR Website

The image shows the VEXcode VR website interface. The top navigation bar includes 'File', 'Tools', 'TUTORIALS', 'LEARN', 'UNDO', 'REDO', 'VEXcode Project', 'Not Saved', and 'SELECT'. The left sidebar features a 'Code' tab, a 'Drivetrain' category with blocks like 'drive forward', 'turn right', and 'stop driving', and other categories: Magnet, Looks, Events, Control, Sensing, Operators, Variables, My Blocks, and Comments. The main workspace displays a 'when started' script with the following sequence of blocks:

- drive forward for 600 mm
- turn right for 90 degrees
- drive forward for 600 mm
- turn right for 90 degrees
- drive forward for 600 mm

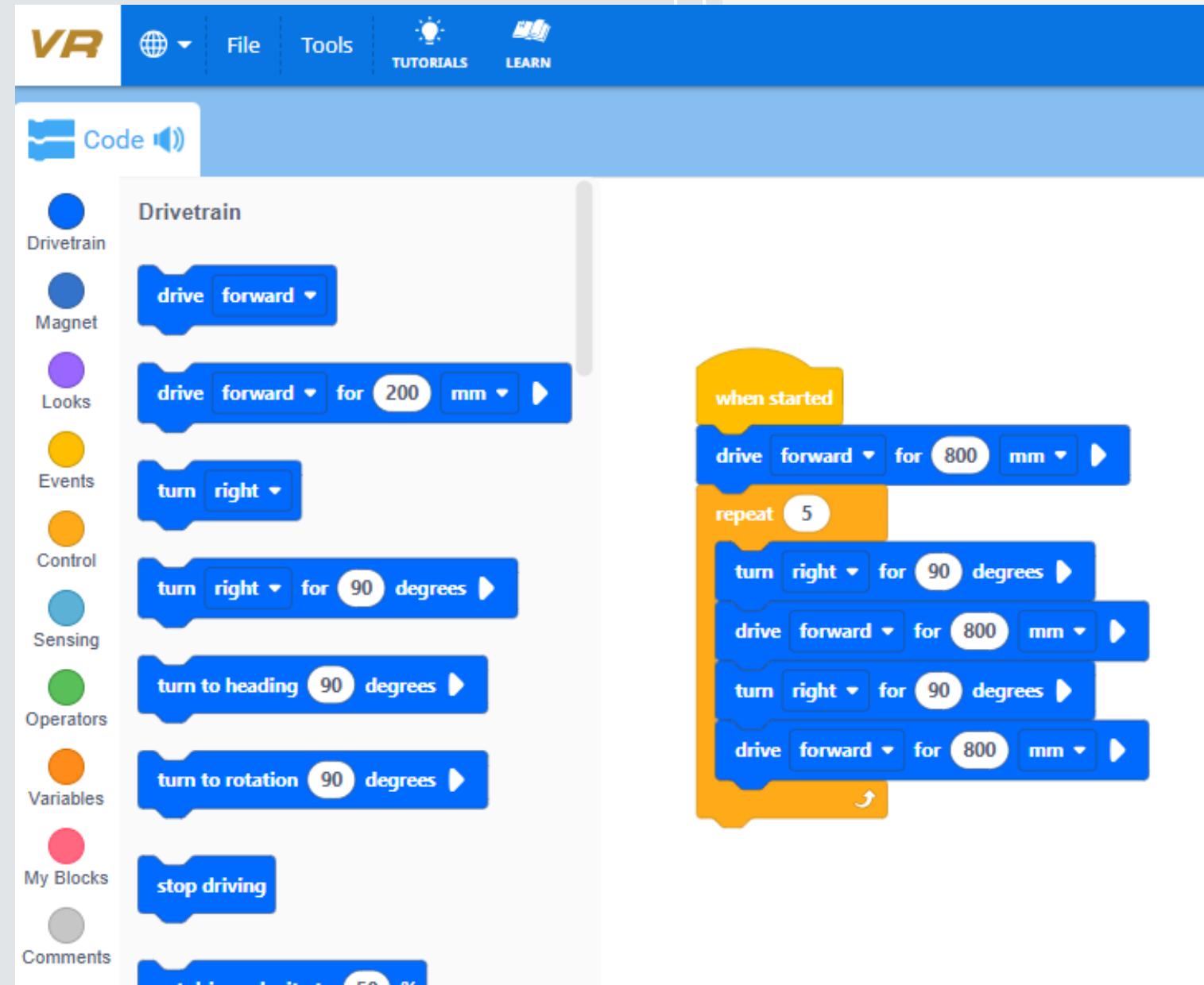
The bottom right corner of the workspace shows a timer at 00:20:6 and icons for camera, video, and microphone. The bottom left corner shows a square icon and a circular icon with a refresh symbol.

```
when started
  drive [forward v] for (600) [mm v]
  turn [right v] for (90) [degrees v]
  drive [forward v] for (600) [mm v]
  turn [right v] for (90) [degrees v]
  drive [forward v] for (600) [mm v]
```

# try this..

1

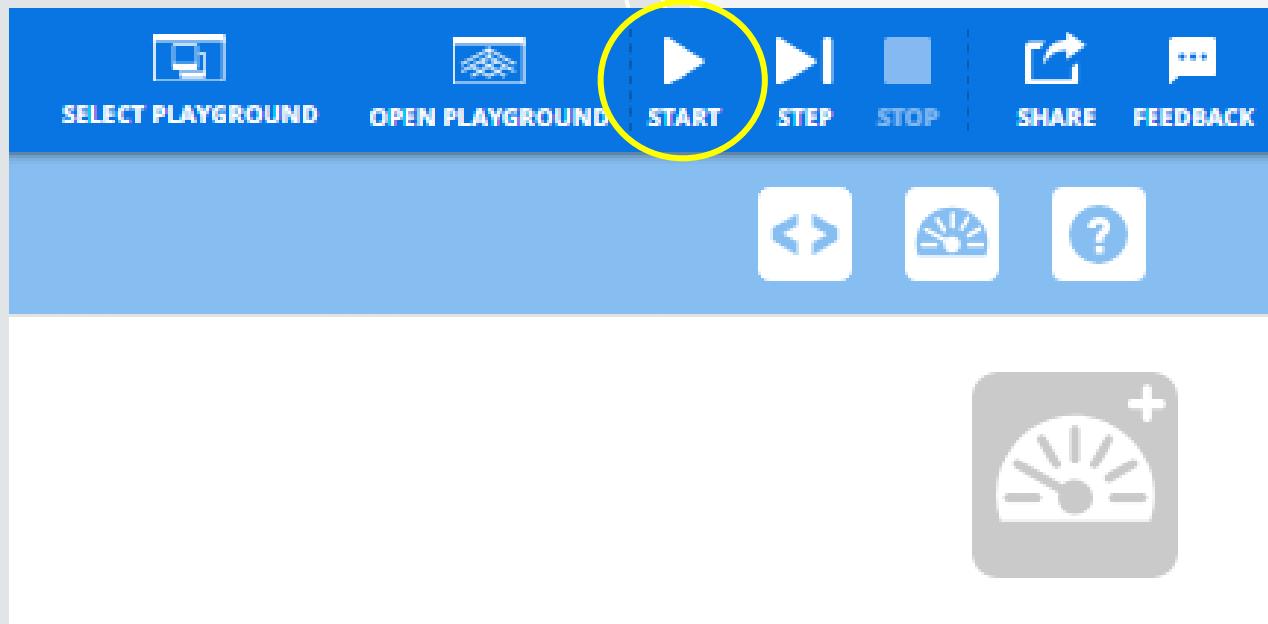
## Assemble code as you wish



# try this..

2

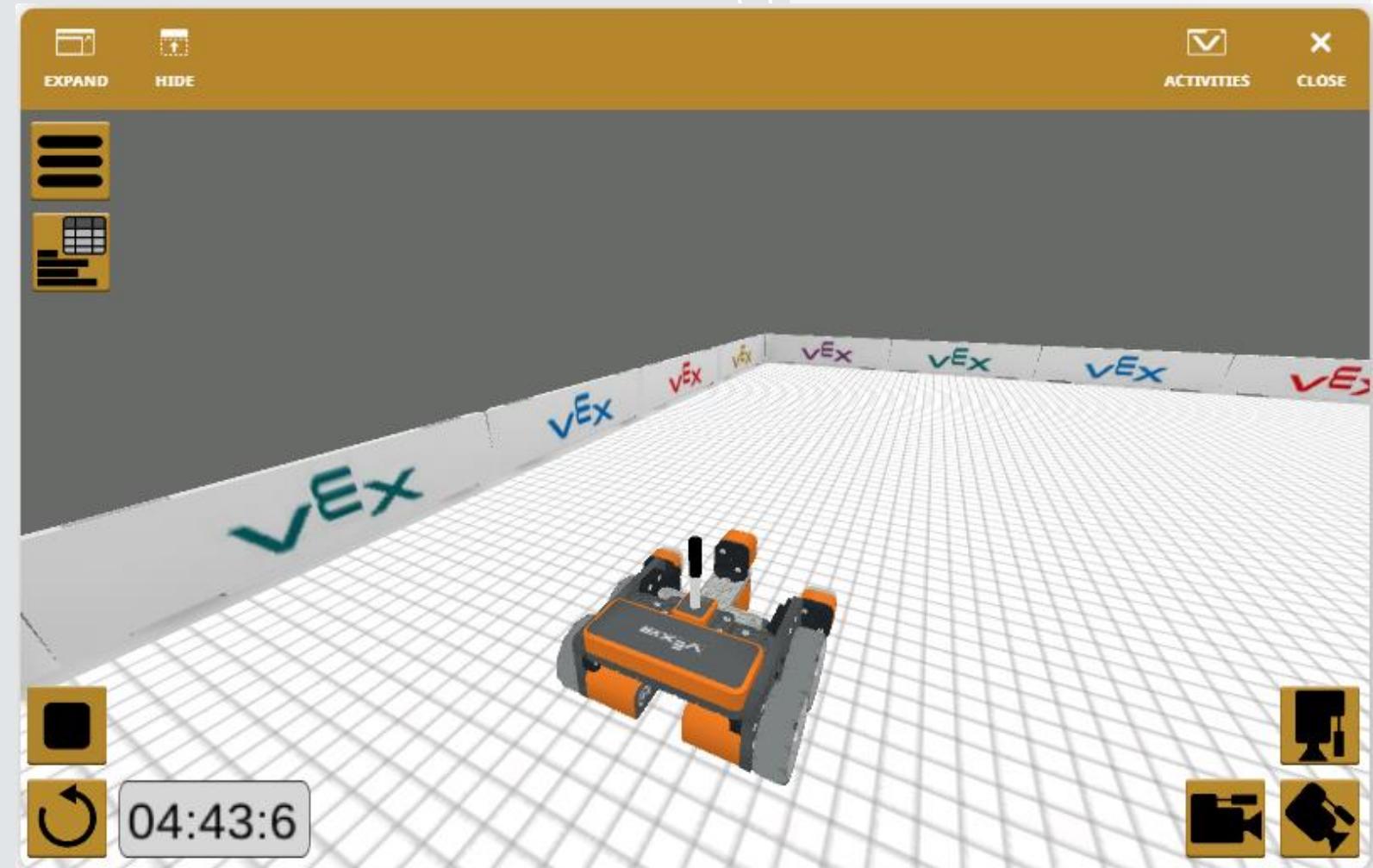
Click 'START'



# try this..

3

- The simulation then appear on your screen
- Select camera icon to change the view angle



For more tutorial,  
check the link below..

<https://www.youtube.com/watch?v=31-yUz5AaRU&list=PL-ptF2sIHTJDcHk2UL57mTy7t6-dIGgZL>

**For more tutorial,  
check the link  
below..**

<https://www.youtube.com/watch?v=31-yUz5AaRU&list=PL-ptF2sIHtJDcHk2UL57mTy7t6-dIGgZL>

